## MATH 261 ALGEBRAIC TOPOLOGY I OPTIONAL PROBLEM SET 4

Due: optional.

- 1. The goal of this problem is to show that  $GL_n(\mathbb{R})$  has two connected components which are distinguished by the sign of the determinant.
  - (i) Briefly explain why O(n) is a deformation retraction of  $GL_n(\mathbb{R})$ . (No need to give a complete proof. Deduce that the inclusion  $O(n) \hookrightarrow GL_n(\mathbb{R})$  induces a bijection on connected components.
  - (ii) Show that, when n > 1, SO(n) acts transitively on  $S^{n-1}$  and that the stabilizer of  $e_n \in S^{n-1}$  is SO(n-1).
  - (iii) Show that the mapping  $SO(n)/SO(n-1) \to S^{n-1}$  that takes  $A \cdot SO(n-1)$  to  $Ae_n$  is a homeomorphism.
  - (iv) Show that if  $n \geq 2$ , then SO(n) is connected if and only if SO(n-1) is connected. Deduce that SO(n) is connected for all  $n \geq 1$  and that O(n) has two connected components.
  - (v) Show that  $GL_n(\mathbb{R})$  has two connected components:

$${A \in GL_n(\mathbb{R}) : \det A > 0}$$
 and  ${A \in GL_n(\mathbb{R}) : \det A < 0}$ .

2. Suppose that V is a real vector space of dimension d, where d > 0. Two ordered bases  $(v_1, \ldots, v_d)$  and  $(w_1, \ldots, w_d)$  of V determine an element A of  $GL_d(\mathbb{R})$  via:

$$(v_1,\ldots,v_d)=(w_1,\ldots,w_d)A.$$

Define two ordered bases to be equivalent if the matrix A that relates them has positive determinant. An *orientation* of V is an equivalence class of ordered bases of V. Denote the equivalence class of the ordered basis  $(v_1, \ldots, v_d)$  by  $[v_1, \ldots, v_d]$ .

- (i) Show that each V has exactly two orientations.
- (ii) Show that if  $\sigma$  is a permutation of  $\{1,\ldots,d\}$ , then

$$[v_{\sigma(1)}, \dots, v_{\sigma(d)}] = \operatorname{sgn}(\sigma)[v_1, \dots, v_d].$$

(The orientation opposite to  $[v_1, \ldots, v_d]$  is denoted by  $-[v_1, \ldots, v_d]$ .)

5. (Orientations of simplices) Suppose that V is a finite dimensional vector space and that  $v_0, \ldots, v_n$  are affine independent elements of V. Denote the simplex  $\langle v_0, \ldots, v_n \rangle$  they span by  $\Delta$ . Show that the vector

space  $T\Delta$  of vectors tangent to  $\Delta$  is

$$T\Delta = \{\sum_{j=0}^{n} a_j v_j : a_j \in \mathbb{R}, \sum_{j=0}^{n} a_j = 0\}.$$

By definition, an orientation of the simplex  $\Delta$  is an orientation of the vector space  $T\Delta$ . Each ordering of the vertices of  $\Delta$  determines an orientation of  $\Delta$  as follows: the orientation determined by the vertex ordering  $v_0 < v_1 < \cdots < v_n$  is defined to be

$$[v_1-v_0,v_2-v_0,\ldots,v_n-v_0].$$

Denote it by  $\langle v_0, \dots, v_n \rangle$ . Show that

(i) if  $1 \leq j \leq n$ , then

$$[v_0 - v_j, v_1 - v_j, \dots, v_{j-1} - v_j, v_{j+1} - v_j, \dots, v_n - v_j]$$

$$= (-1)^j [v_1 - v_0, \dots, v_n - v_0].$$

(ii) if  $\sigma$  is a permutation of  $\{0, 1, \dots, n\}$ , then  $\langle v_{\sigma(0)}, v_{\sigma(1)}, \dots, v_{\sigma(n)} \rangle = \operatorname{sgn}(\sigma) \langle v_0, \dots, v_n \rangle$ .

That is, each ordering of the vertices of a simplex orient the simplex; two orderings determine the same orientation if and only if they differ by an even permutation. This should help explain why we care about and need ordered simplicial complexes.

- 3. The goal of this problem is to show that the orientation induced on the jth face  $\Delta_j$  of  $\langle v_0, \ldots, v_n \rangle$  is  $(-1)^j \langle v_0, \ldots, \widehat{v_j}, \ldots, v_n \rangle$ . We will use the notation of the previous problem.
  - (i) Show that the vector

$$w_j := -v_j + \frac{1}{n+1} \sum_{j=0}^{n} v_j \in T\Delta$$

is an outward normal to the jth face of  $\Delta$ .<sup>2</sup>

(ii) The standard convention for orienting a boundaries ("outward normal first") says that a basis  $u_1, \ldots, u_{n-1}$  of the tangent space  $T\Delta_j$  of the boundary is positively oriented when

$$w_j, u_1, \ldots, u_{n-1}$$

is a positively oriented basis of  $T\Delta$ . (Nothing to prove here!)

<sup>&</sup>lt;sup>1</sup>I admit that this notation is mildly ambiguous. But we will see that it is a convenient abuse of notation. More accurately, when we write  $\langle v_0, \ldots, v_n \rangle$  we will mean the oriented simplex spanned by the ordered set of vectors  $v_0, v_1, \ldots, v_n$ .

<sup>&</sup>lt;sup>2</sup>Here, take  $v_0, v_1, \ldots, v_n$  to be an orthonormal basis of  $\mathbb{R}^{\{v_0, \ldots, v_n\}}$ .

- (iii) Show that the orientation  $\langle v_0, \ldots, v_n \rangle$  of  $\Delta$  induces the orientation  $\langle v_1, \ldots, v_n \rangle$  on the 0th face  $\Delta_0$ . (iv) Use action of the symmetric group of  $\{0, 1, \ldots, n\}$  and the
- (iv) Use action of the symmetric group of  $\{0, 1, ..., n\}$  and the results of the previous problem (or otherwise) to deduce that the the orientation induced on  $\Delta_j$  by  $\langle v_0, ..., v_n \rangle$  is

$$(-1)^j \langle v_0, \dots, \widehat{v_j}, \dots, v_n \rangle.$$